

APPLICATION NOTE 3331

High-Side Current-Sense Amplifier Operates at High Voltage

This circuit modifies a standard 32V high-side current monitor to measure load current (to 30mA) while accommodating any level of high voltage, subject to limitations in the external components. (The components shown allow measurements to 4A.)

The simplest technique for measuring current in an actuator or motor is to monitor its ground current by sensing the voltage drop across a small resistive element, added between the load and ground. Because the device and its associated electronics share the same ground potential, you need only amplify the ground-current signal.

That approach, however, does not detect device shorts to ground, which can overload the high-side drive circuitry. To mitigate such potential fault conditions, a high-side current monitor will detect short circuits and similar faults downstream from the current monitor.

High-side current monitoring has advantages, but its use has been limited by a shortage of devices able to handle the high voltage levels used in industry (from 24V to many 100s of volts). Off-the-shelf devices can operate to 32V and to 76VDC, but even 76VDC is not enough for many applications. **Figure 1** shows a simple way to adapt a standard 32V device for use at any voltage level, subject to limitations in the external components. (The components shown support 130V.) Accuracy is better than 1% for load currents greater than 30mA.

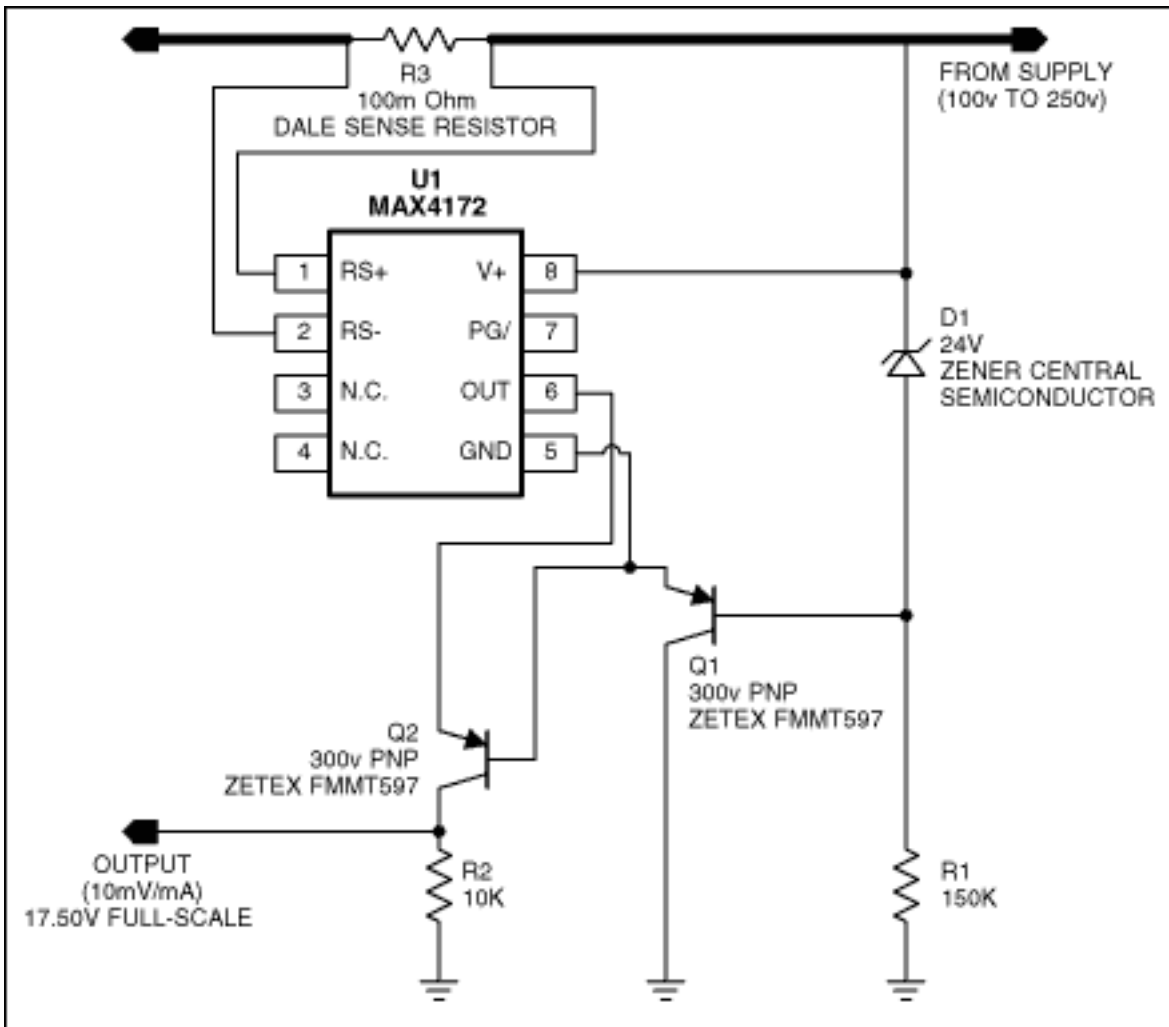


Figure 1. The components shown enable a 36V high-side current-monitoring IC (U1) to operate at common-mode voltages as high as 130V. (For higher voltages, re-size R1 as suggested in the text.)

U1 was selected for its current-output stage, which allows easy implementation of the current mirror necessary for level-shifting the output signal to ground. Then, the ground-referenced signal is easily monitored with an A/D converter or comparator.

In this application, current applied to the load is monitored in the presence of a 130VDC common-mode level. First, ensure that U1's absolute maximum rating (36VDC with respect to the GND pin) is not violated for the RS+, RS-, and V+ pins. For that purpose, the 24V zener diode Z1 limits voltages between the V+, RS+, and GND pins to 24V. Thus, the typical voltage between these pins is 24V minus the V_{be} of Q1, or 23.3V.

I_{zener} for this circuit is approximately $700\mu A$. Note: the manufacturer's suggested bias current is $500\mu A$, but the zener's di/dt slope goes negative below $300\mu A$, which can introduce noise and even oscillation (**Figure 2**). The minimum specified bias ($300\mu A$ to $500\mu A$) sets the maximum value of R1, and the maximum allowed power dissipation for R1 and D1 combined sets the minimum value for R1. Thus, for supply rails between 100V and 250V a reasonable R1 value is between $150k\Omega$ and $225k\Omega$ ($150k\Omega$ in this case).

Central Semi 24V Zener

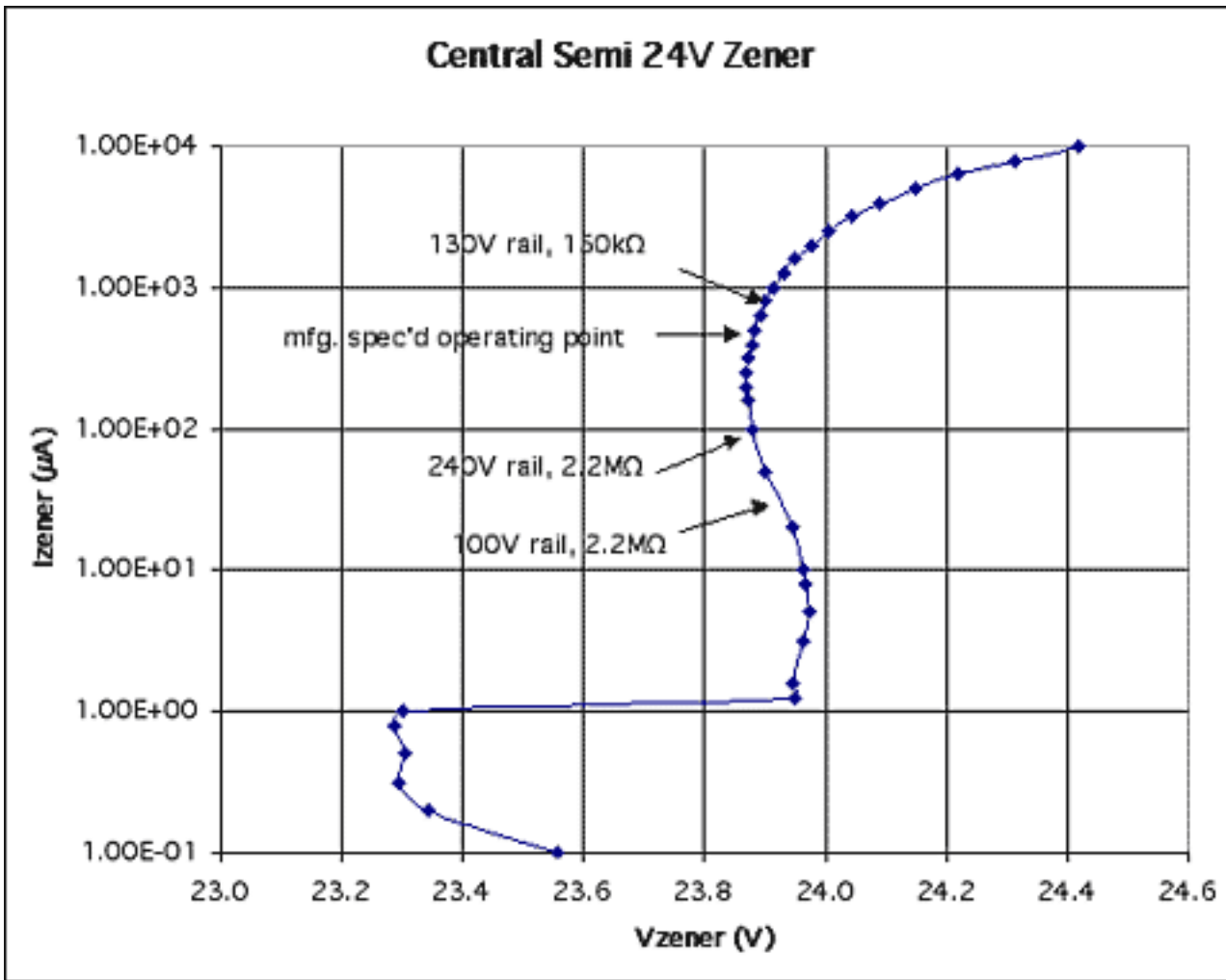


Figure 2. This graph of V_{zener} vs. I_{zener} (for the zener diode in Figure 1) indicates I_{zener} values corresponding to various combinations of high-side voltage and $R1$. For bias currents below $\sim 400\mu A$, note that the slope of this curve (indicating the zener's dynamic source impedance) goes negative, producing additional noise and the possibility of oscillation.

$Q1$ and $R1$ form a shunt regulator. $Q1$ was selected for its maximum V_{CE} rating ($-300V$), its high gain ($100V/V$ at $1.0mA$), and its power-handling capability ($500mW$). Output current is proportional to the voltage difference (V_{sense}) between R_{s+} and R_{s-} : $I_{out} = G_m \times V_{sense}$, where $V_{sense} = R_{sense} \times I_{load}$. G_m for $U1$ is $10mA/V$. If the maximum monitored load current (I_{load}) is $4A$, and $R_{sense} = 10m\Omega$, the maximum I_{out} is $10mA/V \times 10m\Omega \times 4A = 400\mu A$.

Thus, I_{out} is proportional to I_{load} , and the maximum expected output is $400\mu A$. For applications of wide dynamic range in which V_{sense} can approach the absolute-maximum rating of the internal differential pair ($700mV$), you should protect the sense pins by adding series resistors between R_{sense} and R_{s+} , and between R_{sense} and R_{s-} . The resistor values should be selected to limit input currents to $<10mA$ when the R_{s+} to R_{s-} difference is $700mV$.

I_{out} is now proportional to I_{load} , but for easy monitoring it must be level shifted to ground by the current mirror consisting of $Q2$ and $R2$. $Q2$'s high gain forces the collector current to closely approximate the emitter current, which, applied to $R2$, produces a voltage that can be measured at V_{out} . Like $Q1$, $Q2$ needs a maximum V_{ce} rating of $-240V$ minimum (the device shown is rated $-300V$).

V_{out} now equals $I_{out} \times R2$ (the actual output current at $Q2$'s collector is slightly less, due to the outflow of $Q2$ base current.) At $I_{load} = 4A$, $V_{out} = 400\mu A \times 10.0K\Omega = 4.0V$. Designs with lower or higher operating voltage can be accommodated by proper selection of $Q1$, $Q2$, and the base resistor $R1$.

This design idea appeared in the July 22, 2004 issue of *EDN* magazine.

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AN3331, AN 3331, APP3331, Appnote3331, Appnote 3331

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